Solution for the following error

/opt/ros/melodic/lib/move\_base/move\_base: symbol lookup error: /opt/ros/melodic/lib//librange\_sensor\_layer.so: undefined symbol: \_ZN3tf212getTimestampIN13geometry\_msgs13PointStamped\_ISaIvEEEEERKN3ros4TimeERKT\_

Add the following pkgs to catkin\_ws using git clone

* Navigation layers
* People
* Wu\_ros\_tools

<https://github.com/DLu/wu_ros_tools>

<https://github.com/wg-perception/people>

<https://github.com/DLu/navigation_layers>

Add the following pkg to catkin\_ws using sudo apt-get install

* ros-melodic-bfl